§ 23.397

used if hinge moments are based on accurate flight test data, the exact reduction depending upon the accuracy and reliability of the data.

(c) Pilot forces used for design are assumed to act at the appropriate control grips or pads as they would in flight, and to react at the attachments of the control system to the control surface horns.

[Doc. No. 4080, 29 FR 17955, Dec. 18, 1964, as amended by Amdt. 23-7, 34 FR 13089, Aug. 13, 1969]

$\S 23.397$ Limit control forces and torques.

(a) In the control surface flight loading condition, the airloads on movable surfaces and the corresponding deflections need not exceed those that would result in flight from the application of any pilot force within the ranges specified in paragraph (b) of this section. In applying this criterion, the effects of control system boost and servo-mechanisms, and the effects of tabs must be considered. The automatic pilot effort must be used for design if it alone can produce higher control surface loads than the human pilot.

(b) The limit pilot forces and torques are as follows:

Control	Maximum forces or torques for design weight, weight equal to or less than 5,000 pounds ¹	Minimum forces or torques ²
Aileron: Stick	67 lbs 50 D inlbs ⁴	40 lbs. 40 D in lbs. ⁴
Elevator: Stick Wheel (symmetrical) Wheel (unsymmetrical) 5 Rudder	167 lbs 200 lbs 200 lbs	100 lbs. 100 lbs. 100 lbs. 150 lbs.

¹For design weight (W) more than 5,000 pounds, the specified maximum values must be increased linearly with weight to 1.18 times the specified values at a design weight of 12,500 pounds and for commuter category airplanes, the specified values must be increased linearly with weight to 1.35 times the specified values at a design weight of 19,000 pounds.

pounds.

² If the design of any individual set of control systems or surfaces makes these specified minimum forces or torques inapplicable, values corresponding to the present hinge moments obtained under § 23.415, but not less than 0.6 of the specified minimum forces or torques, may be used.

³ The critical parts of the alleron control system must also be designed for a single tangential force with a limit value of 1.25 times the couple force determined from the above criteria

⁴D=wheel diameter (inches).

⁵The unsymmetrical force must be applied at one of the normal handgrip points on the control wheel.

[Doc. No. 4080, 29 FR 17955, Dec. 18, 1964, as amended by Amdt. 23-7, 34 FR 13089, Aug. 13, 1969; Amdt. 23-17, 41 FR 55464, Dec. 20, 1976; Amdt. 23-34, 52 FR 1829, Jan. 15, 1987; Amdt. 23-45, 58 FR 42160, Aug. 6, 1993]

§23.399 Dual control system.

- (a) Each dual control system must be designed to withstand the force of the pilots operating in opposition, using individual pilot forces not less than the greater of—
- (1) 0.75 times those obtained under §23.395; or
- (2) The minimum forces specified in $\S 23.397(b)$.
- (b) Each dual control system must be designed to withstand the force of the pilots applied together, in the same direction, using individual pilot forces not less than 0.75 times those obtained under §23.395.

[Doc. No. 27805, 61 FR 5145, Feb. 9, 1996]

§23.405 Secondary control system.

Secondary controls, such as wheel brakes, spoilers, and tab controls, must be designed for the maximum forces that a pilot is likely to apply to those controls.

§23.407 Trim tab effects.

The effects of trim tabs on the control surface design conditions must be accounted for only where the surface loads are limited by maximum pilot effort. In these cases, the tabs are considered to be deflected in the direction that would assist the pilot. These deflections must correspond to the maximum degree of "out of trim" expected at the speed for the condition under consideration.

§ 23.409 Tabs.

Control surface tabs must be designed for the most severe combination of airspeed and tab deflection likely to be obtained within the flight envelope for any usable loading condition.

§23.415 Ground gust conditions.

(a) The control system must be investigated as follows for control surface loads due to ground gusts and taxiing downwind:

Federal Aviation Administration, DOT

(1) If an investigation of the control system for ground gust loads is not required by paragraph (a)(2) of this section, but the applicant elects to design a part of the control system of these loads, these loads need only be carried from control surface horns through the nearest stops or gust locks and their supporting structures.

(2) If pilot forces less than the minimums specified in §23.397(b) are used for design, the effects of surface loads due to ground gusts and taxiing downwind must be investigated for the entire control system according to the

formula:

H = K c S q

where-

H = limit hinge moment (ft.-lbs.);

- c = mean chord of the control surface
 aft of the hinge line (ft.);
- S = area of control surface aft of the hinge line (sq. ft.);
- q = dynamic pressure (p.s.f.) based on a design speed not less than 14.6 √(W/ S) + 14.6 (f.p.s.) where W/S = wing loading at design maximum weight, except that the design speed need not exceed 88 (f.p.s.);
- K = limit hinge moment factor for ground gusts derived in paragraph
 (b) of this section. (For ailerons and elevators, a positive value of K indicates a moment tending to depress the surface and a negative value of K indicates a moment tending to raise the surface).

(b) The limit hinge moment factor *K* for ground gusts must be derived as follows:

Surface	К	Position of controls
(a) Aileron	0.75	Control column locked lashed in mid-position.
(b) Aileron	±0.50	Ailerons at full throw; + moment on one aileron, - moment on the other.
(c) Elevator	±0.75	(c) Elevator full up (−).
(d) Elevator		(d) Elevator full down (+).
(e) Rudder	±0.75	(e) Rudder in neutral.
(f) Rudder		(f) Rudder at full throw.

(c) At all weights between the empty weight and the maximum weight declared for tie-down stated in the appropriate manual, any declared tie-down points and surrounding structure, control system, surfaces and associated gust locks, must be designed to withstand the limit load conditions that exist when the airplane is tied down

and that result from wind speeds of up to 65 knots horizontally from any direction.

[Doc. No. 4080, 29 FR 17955, Dec. 18, 1964, as amended by Amdt. 23-7, 34 FR 13089, Aug. 13, 1969; Amdt. 23-45, 58 FR 42160, Aug. 6, 1993; Amdt. 23-48, 61 FR 5145, Feb. 9, 1996]

HORIZONTAL STABILIZING AND BALANCING SURFACES

§23.421 Balancing loads.

- (a) A horizontal surface balancing load is a load necessary to maintain equilibrium in any specified flight condition with no pitching acceleration.
- dition with no pitching acceleration.
 (b) Horizontal balancing surfaces must be designed for the balancing loads occurring at any point on the limit maneuvering envelope and in the flap conditions specified in §23.345.

[Doc. No. 4080, 29 FR 17955, Dec. 18, 1964, as amended by Amdt. 23–7, 34 FR 13089, Aug. 13, 1969; Amdt. 23–42, 56 FR 352, Jan. 3, 1991]

§23.423 Maneuvering loads.

Each horizontal surface and its supporting structure, and the main wing of a canard or tandem wing configuration, if that surface has pitch control, must be designed for the maneuvering loads imposed by the following conditions:

- (a) A sudden movement of the pitching control, at the speed V_{A} , to the maximum aft movement, and the maximum forward movement, as limited by the control stops, or pilot effort, whichever is critical.
- (b) A sudden aft movement of the pitching control at speeds above $V_{\rm A}$, followed by a forward movement of the pitching control resulting in the following combinations of normal and angular acceleration:

Condition	Normal accelera- tion (n)	Angular acceleration (radian/sec ₂)
Nose-up pitching Nose-down ptiching	1.0 n _m	$ \begin{array}{l} +39 n_{\rm m} {\div} V {\times} (n_{\rm m} - 1.5) \\ -39 n_{\rm m} {\div} V {\times} (n_{\rm m} - 1.5) \end{array} $

where—

- (1) $n_{\rm m}{=}{positive}$ limit maneuvering load factor used in the design of the airplane; and
 - (2) V=initial speed in knots.

The conditions in this paragraph involve loads corresponding to the loads